3/29/16

Mobile Motion-Tracking Robot Arm

Jeff Ruocco, Jeff Falberg, Getro Jean-Baptiste

**Progress Made Since Previous Session**

Xbees are set up and wireless communication between the Arduino and servo controller is working. Wireless camera is setup and working. Arm movement is smoother.

**Tasks for Next Session**

Jeff R – Opening and closing of gripper

Jeff F – Code wheels for platform

Getro – Finish powering platform